

WICK-TYPE STOCHASTIC KdV EQUATION BASED ON LÉVY WHITE NOISE

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Abstract

Wick-type stochastic KdV equation based on Lévy white noise is researched. Lévy white noise functional solutions are showed by using F -expansion method and Hermite transform in Lévy white noise space. These solutions are classified as Jacobi elliptic function and soliton-like solutions. Some of the obtained soliton-like solutions are sketched graphically.

1. Introduction

It is well known that random waves are important subject of stochastic partial differential equations (SPDEs). There were many researchers studied this subject. In [1], Wadati first introduced and studied the stochastic KdV equation and gave the diffusion of the soliton solution of the KdV equation under Gaussian white noise. The Wick-type stochastic KdV equation on the Gaussian white noise space was first

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introduced by Xie in [2], he showed the Bäcklund transformation and the exact white noise functional solutions by using the homogeneous balance principle. Furthermore, Chen and Xie [3-6], Xie [7-9], Ghany [10-12], Ghany et al. [13], and Ghany and Hyder [14-18] investigated some stochastic travelling wave equations using Gaussian white noise analysis. On the other hand, an extension of Gaussian white noise analysis to non-Gaussian white noise analysis was established in [21], and developed further in [22, 23]. Based on this extension, Løkka et al. [24] and Øksendal [25] developed a white noise framework for the study of SPDEs driven by a d -parameter Lévy white noise, which is in fact a non-Gaussian white noise. Recently, Hyder and Zakarya [20] have developed a non-Gaussian Wick calculus based on the theory of hypercomplex systems $L_1(\mathcal{Q}, dm(x))$. Using the Delsarte characters $\chi_n(x)$, they introduced a χ -Wick product, a χ -Hermite transform on the space of generalized functions H_{-q}^χ and setup a framework to study the stochastic partial differential equations driven by H_{-q}^χ -processes. Moreover, Ghany et al. [19] applied this framework and F -expansion method and gave non-Gaussian white noise functional solutions of χ -Wick-type stochastic KdV equations.

The main objective of this paper is to use the theory introduced in [24-26] to study a Wick-type analogue of the KdV equation, constructed by means of the Lévy measure. Precisely, we give exact white noise functional solutions of Wick-type stochastic KdV equation based on Lévy white noise, which has the general form

$$U_t + f(t)U \diamond U_x + g(t)U_{xxx} = \dot{\eta}(t) \diamond R^\diamond(U, U_x, U_{xxx}), \quad (1.1)$$

where “ \diamond ” is the Lévy Wick product on the Kondratiev space $(\mathcal{S})_{-1}$, namely, $(\mathcal{S})_{-1}$ is the Lévy white noise functional space which is defined in the next section. Equation (1.1) is a special stochastic perturbation of the KdV equation with variable coefficients

$$u_t + f(t)uu_x + g(t)u_{xxx} = 0 \quad (1.2)$$

by random force $\dot{\eta}(t) \diamond R^\diamond(U, U_x, U_{xxx})$, where $f(t)$ and $g(t)$ are bounded measurable or integrable functions on \mathbb{R}_+ , $\dot{\eta}(t)$ is the Lévy white noise, i.e., $\dot{\eta}(t)$ is the time derivative of Lévy process $\eta(t)$, $R(u, u_x, u_{xxx}) = -\alpha uu_x - \beta u_{xxx}$ is a functional of u, u_x , and u_{xxx} for some constants α, β , and R^\diamond is the Wick version of the functional R . As pointed out in [1, 27], the motion of long, unidirectional, weakly non-linear water waves on a channel can be described by Equation (1.2). Moreover, Wang and Wang [28] gave the exact solutions of Equation (1.1) by using the homogeneous balance principle.

In recent years, large amounts of effort have been directed towards finding exact solutions, particularly exact travelling wave solutions, of non-linear partial differential equations. Many powerful methods have been proposed, such as inverse scattering method [29], Bäcklund-Darboux transformation, F -expansion method [30] and so on.

Our first interest in this work is to implement new strategies that give exact solutions of the Wick-type stochastic KdV equation based on Lévy white noise. The strategies that will be pursued in this work rest mainly on Lévy Hermite transform, Lévy white noise theory, and F -expansion method, all of which are employed to find exact Lévy white noise functional solutions of Equation (1.1). The proposed schemes, as we believe, are entirely new and introduce new solutions in addition to the well-known traditional solutions. The ease of using these methods shows its power to determine shock or solitary type of solutions.

2. Some Basic Concepts about SPDEs Driven by Lévy White Noise

Assume that the Lévy measure ν satisfies the following integrability condition: For all $\epsilon > 0$, there exists $\lambda > 0$ such that

$$\int_{|\theta| \geq \epsilon} \exp(\lambda|\theta|) \nu(d\theta) < \infty. \quad (2.1)$$

This implies that ν has finite moments of order n for all $n \geq 2$. Let $\{\ell_m\}_{m \geq 0}$ be the orthogonalization of $\{1, \theta, \theta^2, \dots\}$ with respect to the inner product of $L^2(\rho)$, where $d\rho(\theta) := \theta^2 \nu(d\theta)$. Then, define the polynomials

$$p_m(\theta) := \frac{\theta \ell_{m-1}(\theta)}{\|\ell_{m-1}\|_{L^2(\rho)}}, \quad m \geq 1. \quad (2.2)$$

The polynomials $\{p_m\}_{m \geq 1}$ form an orthonormal basis for $L^2(\nu)$ (see [31]).

Let $h_n(x)$ be the n -order Hermite polynomials. Put $\xi_n(x) = e^{-\frac{1}{2}x^2} h_n(\sqrt{2x}) / (\pi(n-1)!)^{\frac{1}{2}}$; $n \geq 1, x \in \mathbb{R}$. We have that the collection $\{\xi_n\}_{n \geq 1}$ constitutes an orthogonal basis for $L^2(\mathbb{R})$. If we denote $\alpha = (\alpha_1, \dots, \alpha_d)$ being d -dimensional multi-indices with $\alpha_1, \dots, \alpha_d \in \mathbb{N}$, we have that the family of tensor products $\xi_\alpha = \xi_{(\alpha_1, \dots, \alpha_d)} = \xi_{\alpha_1} \otimes \dots \otimes \xi_{\alpha_d}$; $\alpha \in \mathbb{N}^d$ forms an orthogonal basis for $L^2(\mathbb{R}^d)$. Let $\alpha^{(i)} = (\alpha_1^{(i)}, \dots, \alpha_d^{(i)})$ be the i -th multi-index number in some fixed ordering of all d -dimensional multi-indices $\alpha = (\alpha_1, \dots, \alpha_d) \in \mathbb{N}^d$. We can, and will, assume that this ordering has the property that $i < j \Rightarrow \alpha_1^{(i)} + \alpha_2^{(i)} + \dots + \alpha_d^{(i)} \leq \alpha_1^{(j)} + \alpha_2^{(j)} + \dots + \alpha_d^{(j)}$.

To simplify the notation, we write from now on

$$\xi_i(x) := \xi_{\alpha^{(i)}}(x) = \xi_{\alpha_1^{(i)}} \otimes \dots \otimes \xi_{\alpha_d^{(i)}}; \quad i \geq 1, x \in \mathbb{R}^d.$$

Define the bijective map $\kappa : \mathbb{N} \times \mathbb{N} \rightarrow \mathbb{N}$ by

$$\kappa(i, j) = j + (i + j - 2)(i + j - 1) / 2.$$

Then if $k = \kappa(i, j)$, we define

$$\delta_\kappa(x, \theta) = \delta_{\kappa(i, j)}(x, \theta) = \xi_i(x) p_j(\theta); \quad (i, j) \in \mathbb{N} \times \mathbb{N}, (x, \theta) \in \mathbb{R}^d \times \mathbb{R}.$$

We denote multi-indices as elements of the space $(\mathbb{N}_0^{\mathbb{N}})_c$ of all sequences $\alpha = (\alpha_1, \alpha_2, \dots)$ with elements $\alpha_i \in \mathbb{N}_0$ and with compact support, i.e., with only finitely many $\alpha_i \neq 0$. We define $\mathcal{J} = (\mathbb{N}_0^{\mathbb{N}})_c$. Further, we set $\text{Index}(\alpha) = \max\{i : \alpha_i \neq 0\}$ and $|\alpha| = \sum_i \alpha_i$ for $\alpha \in \mathcal{J}$.

Now, assume $\text{Index}(\alpha) = j$ and $|\alpha| = m$ for $\alpha \in \mathcal{J}$ and identify the function $\delta^{\otimes \alpha}$ as

$$\begin{aligned} \delta^{\otimes \alpha}((x_1, \theta_1), \dots, (x_m, \theta_m)) &= \delta_1^{\otimes \alpha_1} \otimes \dots \otimes \delta_j^{\otimes \alpha_j}((x_1, \theta_1), \dots, (x_m, \theta_m)) \\ &= \delta_1(x_1, \theta_1) \dots \delta_1(x_{\alpha_1}, \theta_{\alpha_1}) \dots \delta_j(x_{\alpha_1+\dots+\alpha_{j-1}+1}, \theta_{\alpha_1+\dots+\alpha_{j-1}+1}) \dots \delta_j(x_m, \theta_m), \end{aligned}$$

where the terms with zero-components α_i are set equal to 1 in the product ($\delta_i^{\otimes 0} = 1$). Also, we define the symmetrized tensor product of the δ_k 's denoted by $\widehat{\delta^{\otimes \alpha}}$ as

$$\begin{aligned} \widehat{\delta^{\otimes \alpha}}((x_1, \theta_1), \dots, (x_m, \theta_m)) &= \widehat{\delta^{\otimes \alpha}}((x_1, \theta_1), \dots, (x_m, \theta_m)) \\ &= \widehat{\delta_1^{\otimes \alpha_1}} \widehat{\otimes} \dots \widehat{\otimes} \widehat{\delta_j^{\otimes \alpha_j}}((x_1, \theta_1), \dots, (x_m, \theta_m)), \end{aligned}$$

where “ $\widehat{\cdot}$ ” denotes symmetrization. For $\alpha \in \mathcal{J}$, we define the random variable

$$K_\alpha = K_\alpha(\omega) = I_{|\alpha|}(\widehat{\delta^{\otimes \alpha}})(\omega); \quad \omega \in \mathcal{S}'(\mathbb{R}^d),$$

where $I_{|\alpha|}$ is the iterated integral of order $m = |\alpha|$ with respect to the compensated jump measure of $\eta(\cdot)$, and $\mathcal{S}'(\mathbb{R}^d)$ is the space of tempered distributions [26].

For a fixed $n \in \mathbb{N}$, letting the space $(\mathcal{S})_1^n$ is composed of those $f(\omega) = \sum_{\alpha} c_{\alpha} K_{\alpha}(\omega) \in \bigoplus_{k=1}^n L^2(\mu)$ with $c_{\alpha} \in \mathbb{R}^n$ such that $\|f\|_{1,k}^2 = \sum_{\alpha} c_{\alpha}^2 (\alpha!)^2 (2\mathbb{N})^{k\alpha} < \infty$, $\forall k \in \mathbb{N}$ with $c_{\alpha}^2 = |c_{\alpha}|^2 = \sum_{k=1}^n (c_{\alpha}^{(k)})^2$ if $c_{\alpha} = (c_{\alpha}^{(1)}, \dots, c_{\alpha}^{(n)}) \in \mathbb{R}^n$, and μ is the Lévy white noise measure on $(\mathcal{S}'(\mathbb{R}), \mathcal{B}(\mathcal{S}'(\mathbb{R})))$, $\alpha! = \prod_{k=1}^{\infty} \alpha_k!$ and $(2\mathbb{N})^{\alpha} = \prod_j (2j)^{\alpha_j}$ for $\alpha \in \mathcal{J}$.

The space $(\mathcal{S})_{-1}^n$ consist of all formal expansions $F(\omega) = \sum_{\alpha} b_{\alpha} K_{\alpha}(\omega)$ with $b_{\alpha} \in \mathbb{R}^n$ such that $\|F\|_{-1,-q}^2 = \sum_{\alpha} b_{\alpha}^2 (2\mathbb{N})^{-q\alpha} < \infty$ for some $q \in \mathbb{N}$. The family of seminorms $\|f\|_{1,k}$, $k \in \mathbb{N}$ gives rise to a topology on $(\mathcal{S})_1^n$, and we can regard $(\mathcal{S})_{-1}^n$ as the dual of $(\mathcal{S})_1^n$ by the action $\langle F, f \rangle = \sum_{\alpha} (b_{\alpha}, c_{\alpha}) \alpha!$, where (b_{α}, c_{α}) is the usual inner product in \mathbb{R}^n .

The Wick product $F \diamond G$ of two elements $F = \sum_{\alpha} a_{\alpha} K_{\alpha}$, $G = \sum_{\alpha} b_{\alpha} K_{\alpha} \in (\mathcal{S})_{-1}^n$ with $a_{\alpha}, b_{\alpha} \in \mathbb{R}^n$, is defined by

$$F \diamond G = \sum_{\alpha, \beta} (a_{\alpha}, b_{\beta}) K_{\alpha+\beta}.$$

One can prove that the spaces $\mathcal{S}(\mathbb{R}^d)$, $\mathcal{S}'(\mathbb{R}^d)$, $(\mathcal{S})_1$, and $(\mathcal{S})_{-1}$ are closed under Wick product.

For $F = \sum_{\alpha} a_{\alpha} K_{\alpha} \in (\mathcal{S})_{-1}^n$ with $a_{\alpha} \in \mathbb{R}^n$, the Lévy Hermite transform of F , denoted by $\mathcal{H}(F)$ or \tilde{F} , is defined by

$$\mathcal{H}(F)(z) = \tilde{F}(z) = \sum_{\alpha} a_{\alpha} z^{\alpha} \in \mathbb{C}^n \quad (\text{when convergent}),$$

where $z = (z_1, z_2, \dots) \in \mathbb{C}^{\mathbb{N}}$ (the set of all sequences of complex numbers) and $z^{\alpha} = z_1^{\alpha_1} z_2^{\alpha_2} \dots z_n^{\alpha_n} \dots$ for $\alpha = (\alpha_1, \alpha_2, \dots) \in \mathcal{J}$.

For $F, G \in (\mathcal{S})_{-1}^n$ by this definition, we have

$$\widetilde{F \diamond G}(z) = \widetilde{F}(z) \cdot \widetilde{G}(z),$$

for all z such that $\widetilde{F}(z), \widetilde{G}(z)$ exist. The product on the right-hand side of the above formula is the complex bilinear product between two elements of $\mathbb{C}^{\mathbb{N}}$ defined by $(z_1^{(1)}, \dots, z_n^{(1)}), (z_1^{(2)}, \dots, z_n^{(2)}) = \sum_{k=1}^n z_k^{(1)} z_k^{(2)}$, where $z_k^{(i)} \in \mathbb{C}$.

Let $F = \sum_{\alpha} a_{\alpha} K_{\alpha} \in (\mathcal{S})_{-1}^n$. Then the vector $\widetilde{F}(0) \in \mathbb{R}^n$ is called the generalized expectation of F and is denoted by $\mathbb{E}(F)$. Suppose that $X : V \rightarrow \mathbb{C}^m$ is an analytic function, where V is a neighbourhood of $\mathbb{E}(F)$. Assume that the Taylor series of X around $\mathbb{E}(F)$ has coefficients in \mathbb{R}^n . Then the Wick version $X^{\diamond}(F) = \mathcal{H}^{-1}(X \circ \widetilde{F}) \in (\mathcal{S})_{-1}^m$.

Suppose that modelling considerations lead us to consider an SPDE expressed formally as $A(t, x, \partial_t, \nabla_x, U, \omega) = 0$, where A is some given function, $U = U(x, t, \omega)$ is the unknown (generalized) stochastic process, and where the operators $\partial_t = \frac{\partial}{\partial t}$, $\nabla_x = (\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_d})$ when $x = (x_1, \dots, x_d) \in \mathbb{R}^d$. Firstly, we interpret all products as Wick products and all functions as their Wick versions. We indicate this as

$$A^{\diamond}(t, x, \partial_t, \nabla_x, U, \omega) = 0. \quad (2.3)$$

Secondly, we take the Lévy Hermite transform of (2.3). This turns Wick products into ordinary products (between complex numbers) and the equation takes the form

$$\widetilde{A}(t, x, \partial_t, \nabla_x, \widetilde{U}, z_1, z_2, \dots) = 0, \quad (2.4)$$

where $\widetilde{U} = \mathcal{H}U$ is the Lévy Hermite transform of U and z_1, z_2, \dots are complex numbers. Suppose we can find a solution $u = u(x, t, z)$ of the

equation $\tilde{A}(t, x, \partial_t, \nabla_x, u, z) = 0$, for each $z = (z_1, z_2, \dots) \in \mathbb{V}_q(r)$ for some q, r , where $\mathbb{V}_q(r) = \{z = (z_1, z_2, \dots) \in \mathbb{C}^{\mathbb{N}} : \sum_{\alpha \neq 0} |z^\alpha|^2 (2\mathbb{N})^{q\alpha} < r^2\}$. Then, under certain conditions, we can take the inverse Lévy Hermite transform $U = \mathcal{H}^{-1}u \in (\mathcal{S})_{-1}$ and thereby obtain a solution U of the original (Wick) equation (2.3). Sufficient conditions for this procedure to work are given in the next theorem.

Theorem 2.1 ([25, 26]). *Suppose $u(x, t, z)$ is a solution of the Lévy Hermite transformed equation (2.4) for (x, t) in some bounded open set $\mathbf{D} \in \mathbb{R}^d \times \mathbb{R}_+$, and for all $z \in \mathbb{V}_q(r)$ some q, r . Moreover, suppose that $u(x, t, z)$ and all its partial derivatives, which are involved in Equation (2.4), are uniformly bounded for $(x, t, z) \in \mathbf{D} \times \mathbb{V}_q(r)$, continuous with respect to $(x, t) \in D$ for all $z \in \mathbb{V}_q(r)$ and analytic with respect to $z \in \mathbb{V}_q(r)$ for all $(x, t) \in \mathbf{D}$. Then there exists $U(x, t) \in (\mathcal{S})_{-1}$ such that $u(x, t, z) = (\tilde{U}(x, t))(z)$ for all $(x, t, z) \in \mathbf{D} \times \mathbb{V}_q(r)$ and $U(x, t)$ solves Equation (2.3) in $(\mathcal{S})_{-1}$.*

3. Lévy White Noise Functional Solutions for Equation (1.1)

In this section, first we reduce Equation (1.1) into a deterministic partial differential equation by applying Lévy Hermite transform. Further, by applying proper transformation, the obtained partial differential equation can be converted into a non-linear ordinary differential equation. Then, by employed the proposed F -expansion method, we obtain a family of exact solutions for the formulated partial differential equation. Then, by using Theorem 2.1 for $d = 1$, we can take the inverse Lévy Hermite transform and thereby obtain Lévy white noise functional solutions of Equation (1.1).

Taking the Lévy Hermite transform of Equation (1.1), we get the deterministic equation

$$\tilde{U}_t(x, t, z) + (f(t) + \alpha\tilde{\eta}(t, z))\tilde{U}(x, t, z)\tilde{U}_x(x, t, z) + (g(t) + \beta\tilde{\eta}(t, z))\tilde{U}_{xxx}(x, t, z) = 0, \quad (3.1)$$

where the Lévy Hermite transform of $\dot{\eta}(t)$ is defined by $\tilde{\eta}(t, z) = \left(\int_{\mathbb{R}} \theta^2 \nu(d\theta) \right)^{1/2} \sum_{i=1}^{\infty} \xi_i(t) z_{\kappa(i,1)}$ when $z = (z_1, z_2, \dots) \in (\mathbb{C}^{\mathbb{N}})_c$ is a vector parameter. For sake of simplicity, let $u(x, t, z) = \tilde{U}(x, t, z)$, $\bar{f}(t, z) = f(t) + \alpha\tilde{\eta}(t, z)$ and $\bar{g}(t, z) = g(t) + \beta\tilde{\eta}(t, z)$.

We seek the travelling wave solution of Equation (3.1) of the form

$$u(x, t, z) = \varphi(\zeta(x, t, z)), \quad \zeta(x, t, z) = l(t, z)x + m(t, z), \quad (3.2)$$

where $l(t, z)$, $m(t, z)$ are functions to be determined later. Substituting Equation (3.2) into Equation (3.1) yields a non-linear ordinary differential equation for $\varphi(\cdot)$

$$(l_t(t, z)x + m_t(t, z))\varphi'(\zeta) + \bar{f}(t, z)l(t, z)\varphi(\zeta)\varphi'(\zeta) + \bar{g}(t, z)l^3(t, z)\varphi'''(\zeta) = 0. \quad (3.3)$$

In Equation (3.3), considering the homogeneous balance between $\varphi(\zeta)\varphi'(\zeta)$ and $\varphi'''(\zeta)$, we can suppose that $\varphi(\cdot)$ can be expressed in the following form:

$$\varphi(\zeta) = A(t, z) + B(t, z)\Phi(\zeta) + C(t, z)\Phi^2(\zeta), \quad (3.4)$$

where $A(t, z)$, $B(t, z)$, and $C(t, z)$ are functions to be determined later and $\Phi(\cdot)$ satisfies the elliptic equation

$$(\Phi'(\zeta))^2 = c_0 + c_1\Phi^2(\zeta) + c_2\Phi^4(\zeta), \quad (3.5)$$

where c_0 , c_1 , and c_2 are arbitrary constants. Substituting (3.4) and (3.5) into (3.3) and setting the coefficients of Φ^i , $\Phi^i\Phi'$ ($i = 0, 1, 2, 3$) to zero,

respectively, we can deduce the following system of equations in the unknowns $A(t, z)$, $B(t, z)$, $C(t, z)$, $l(t, z)$, and $m(t, z)$.

$$A_t = B_t = C_t = 0, \quad (3.6)$$

$$B(xl_t + m_t + \bar{f}Al + \bar{g}l^3c_1) = 0, \quad (3.7)$$

$$2C(xl_t + m_t) + \bar{f}B^2l + 8c_1\bar{g}l^3C + 2\bar{f}ACl = 0, \quad (3.8)$$

$$3Bl(2\bar{g}l^2c_2 + \bar{f}C) = 0, \quad (3.9)$$

$$2Cl(\bar{f}C + 12\bar{g}l^2c_2) = 0. \quad (3.10)$$

From Equation (3.6), we have

$$A(t, z) = \sigma_0, \quad B(t, z) = \sigma_1, \quad C(t, z) = \sigma_2, \quad (3.11)$$

where σ_0 , σ_1 , and σ_2 are arbitrary constants. It follows from Equations (3.7) and (3.8) that

$$l(t, z) = L, \quad (3.12)$$

where $L \neq 0$ is an arbitrary constant. In view of Equations (3.10) and (3.12), we obtain

$$C(t, z) = -\frac{12c_2L^2\bar{g}(t, z)}{\bar{f}(t, z)}. \quad (3.13)$$

By virtue of Equations (3.11) and (3.13), we deduce that $\bar{f}(t, z)$ and $\bar{g}(t, z)$ are linearly dependant, that is

$$\bar{g}(t, z) = \gamma_0\bar{f}(t, z), \quad \text{for all } (t, z) \in \mathbb{R}_+ \times (\mathbb{C}^{\mathbb{N}})_c, \quad (3.14)$$

where γ_0 is an arbitrary constant. Substituting Equation (3.14) into Equation (3.13), we get

$$C(t, z) = -12\gamma_0L^2c_2. \quad (3.15)$$

According to Equation (3.9), we obtain

$$B(t, z) = \sigma_1 = 0. \quad (3.16)$$

Inserting Equations (3.12), (3.15), and (3.16) into Equation (3.8), gives

$$A(t, z) = \sigma_0 = -\frac{m_t(t, z)}{L\bar{f}(t, z)} - 4\gamma_0 L^2 c_1. \quad (3.17)$$

Since σ_0 is an arbitrary constant, we can assume that

$$-\frac{m_t(t, z)}{L\bar{f}(t, z)} = \gamma_1, \quad (3.18)$$

where γ_1 is an arbitrary constant. It follows from Equations (3.17) and (3.18) that

$$m(t, z) = -L\gamma_1 \int_0^t \bar{f}(\tau, z) d\tau, \quad A(t, z) = \gamma_1 - 4\gamma_0 L^2 c_1. \quad (3.19)$$

Therefore, we deduce the solution of Equation (3.1) as follows:

$$u(x, t, z) = \gamma_1 - 4\gamma_0 c_1 L^2 - 12\gamma_0 c_2 L^2 \Phi^2(\zeta(x, t, z)), \quad (3.20)$$

with

$$\zeta(x, t, z) = L \left(x - \gamma_1 \int_0^t [f(\tau) + \alpha \tilde{\eta}(\tau, z)] d\tau \right). \quad (3.21)$$

If we can prove that there exist a bounded open set $D \subset \mathbb{R} \times \mathbb{R}_+$, $q > 0$ and $r > 0$ such that $u(x, t, z)$, $u_t(x, t, z)$, $u_x(x, t, z)$, and $u_{xxx}(x, t, z)$ are uniformly bounded for $(x, t, z) \in D \times \mathbb{V}_q(r)$, continuous with respect to $(x, t) \in D$ for all $z \in \mathbb{V}_q(r)$ and analytic with respect to $z \in \mathbb{V}_q(r)$ for all $(x, t) \in D$. Theorem 2.1 shows that there exists $U(x, t) \in (\mathcal{S})_{-1}$ such that $u(x, t, z) = \mathcal{H}(U(x, t))(z)$ for all $(x, t, z) \in D \times \mathbb{V}_q(r)$ and $U(x, t)$ solves Equation (1.1) in $(\mathcal{S})_{-1}$. From the above, we have that $U(x, t)$ is the inverse Lévy Hermite transform of

$u(x, t, z)$. Hence, by Equations (3.20) and (3.21), we have the Lévy white noise functional solution of Equation (1.1) as follows:

$$U(x, t) = \gamma_1 - 4\gamma_0 c_1 L^2 - 12\gamma_0 c_2 L^2 \Phi^{\diamond 2}(\Theta(x, t)), \quad (3.22)$$

with

$$\Theta(x, t) = L \left(x - \gamma_1 \alpha \eta(t) - \gamma_1 \int_0^t f(\tau) d\tau \right). \quad (3.23)$$

In view of the relation $\exp^{\diamond}(\eta(t)) = \exp(\eta(t) - t^2/2)$ (see [26]), the Lévy white noise functional solution of Equation (1.1) can be given in non-Wick version in the form

$$U(x, t) = \gamma_1 - 4\gamma_0 c_1 L^2 - 12\gamma_0 c_2 L^2 \Phi^2(\Theta(x, t)), \quad (3.24)$$

with

$$\Theta(x, t) = L \left(x - \gamma_1 \alpha \left(\eta(t) - \frac{t^2}{2} \right) - \gamma_1 \int_0^t f(\tau) d\tau \right). \quad (3.25)$$

In fact, there are different Jacobi elliptic function solutions for Equation (3.5), these solutions come from setting different values for the parameters c_0 , c_1 , and c_2 , see Table 1. Therefore, by using Equations (3.24), (3.25) and Table 1, we can get various stochastic Jacobi elliptic function and soliton-like solutions for Equation (1.1). We give two cases as examples:

(I) For $c_0 = 1$, $c_1 = -(1 + m^2)$, and $c_2 = m^2$, ($0 < m < 1$), the solution of Equation (3.5) is $\Phi(\zeta(x, t, z)) = \text{sn}(\zeta(x, t, z))$. Thus, the solution of Equation (3.1) is

$$u_1(x, t, z) = \gamma_1 + 4\gamma_0 L^2 (1 + m^2) - 12\gamma_0 L^2 m^2 \text{sn}^2(\zeta(x, t, z)), \quad (3.26)$$

with $\zeta(x, t, z)$ being defined by Equation (3.21).

Table 1. Some Jacobi elliptic function solutions for Equation (3.5), where m is the Jacobi function module

c_0	c_1	c_2	Φ
1	$-(1 + m^2)$	m^2	sn
$1 - m^2$	$2m^2 - 1$	$-m^2$	cn
$m^2 - 1$	$2 - m^2$	-1	dn
m^2	$-(1 + m^2)$	1	ns
$-m^2$	$2m^2 - 1$	$1 - m^2$	nc
-1	$2 - m^2$	$1 - m^2$	nd
1	$2 - m^2$	$1 - m^2$	sc

The properties of the Jacobian elliptic function $\text{sn}(x)$ (see Chapter 10 in [32]) shows that the conditions of Theorem 2.1 are all satisfied. Hence, there is a stochastic process $U_1(x, t) \in (\mathcal{S})_{-1}$ which is the inverse Lévy Hermite transform of $u_1(x, t, z)$. Therefore, we have the following stochastic Jacobi elliptic function solution of Equation (1.1):

$$U_1(x, t) = \gamma_1 + 4\gamma_0 L^2(1 + m^2) - 12\gamma_0 L^2 m^2 \text{sn}^2(\Theta(x, t)), \quad (3.27)$$

with $\Theta(x, t)$ being defined by Equation (3.25).

In the limit case when $m \rightarrow 1$, we have $\text{sn}(\zeta) \rightarrow \tanh(\zeta)$. Thus, we can get a stochastic soliton-like solution for Equation (1.1) in the form

$$U_1^*(x, t) = \gamma_1 + 8\gamma_0 L^2 - 12\gamma_0 L^2 \tanh^2(\Theta(x, t)), \quad (3.28)$$

where $\Theta(x, t)$ is defined by Equation (3.25).

(II) For $c_0 = 1 - m^2$, $c_1 = 2m^2 - 1$, and $c_2 = -m^2$, ($0 < m < 1$), the solution of Equation (3.5) is $\Phi(\zeta(x, t, z)) = \text{cn}(\zeta(x, t, z))$. Thus, the solution of Equation (3.1) is

$$u_2(x, t, z) = \gamma_1 - 4\gamma_0 L^2(2m^2 - 1) + 12\gamma_0 L^2 m^2 \text{cn}^2(\zeta(x, t, z)), \quad (3.29)$$

with $\zeta(x, t, z)$ being defined by Equation (3.21).

The properties of the Jacobian elliptic function $\text{cn}(x)$ (see Chapter 10 in [32]) shows that the conditions of Theorem 2.1 are all satisfied. Hence, there is a stochastic process $U_2(x, t) \in (\mathcal{S})_{-1}$ which is the inverse Lévy Hermite transform of $u_2(x, t, z)$. Therefore, we have the following stochastic Jacobi elliptic function solution of Equation (1.1):

$$U_2(x, t) = \gamma_1 - 4\gamma_0 L^2 (2m^2 - 1) + 12\gamma_0 L^2 m^2 \text{cn}^2(\Theta(x, t)), \quad (3.30)$$

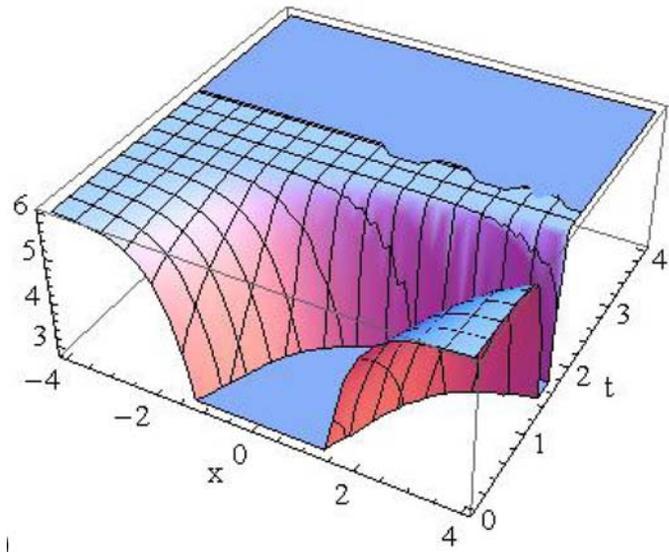
where $\Theta(x, t)$ is defined by Equation (3.25).

For $m \rightarrow 1$, we have $\text{cn}(\zeta) \rightarrow \text{sech}(\zeta)$. Thus, Equation (3.30) gives a stochastic soliton-like solution for Equation (1.1) in the form

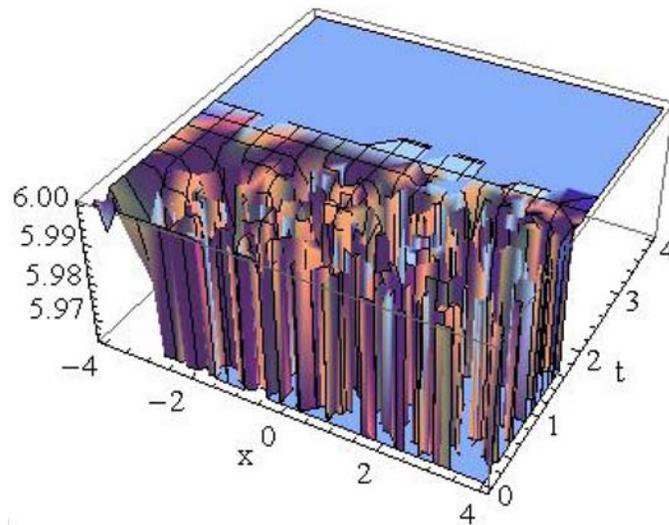
$$U_2^*(x, t) = \gamma_1 - 4\gamma_0 L^2 + 12\gamma_0 L^2 \text{sech}^2(\Theta(x, t)), \quad (3.31)$$

with $\Theta(x, t)$ which is defined by Equation (3.25).

The behaviours of the obtained solutions in Equations (3.28) and (3.31) are shown graphically in Figure 1 and 2 for given parameters. Figure 1 represents the evolutional behaviours of the solution in Equation (3.28) with and without effect of Lévy white noise. Also, Figure 2 presents the behaviours of the solution in Equation (3.31) with and without effect of Lévy white noise. Hence, it is concluded that the stochastic forcing term leads to the uncertainty of the wave amplitude.

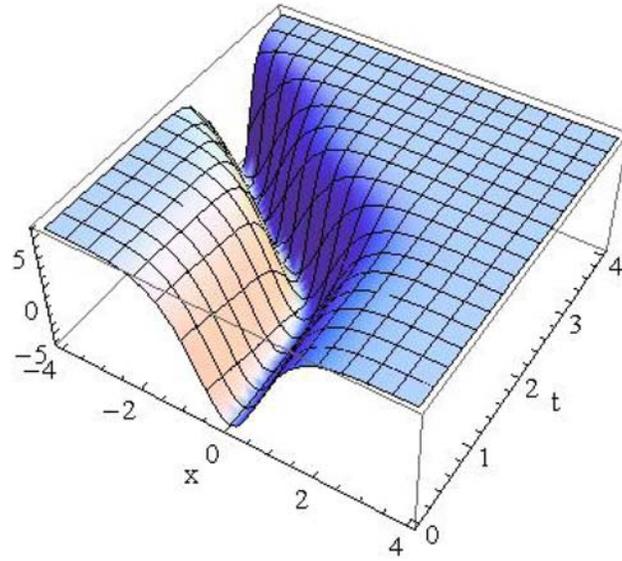


(a)

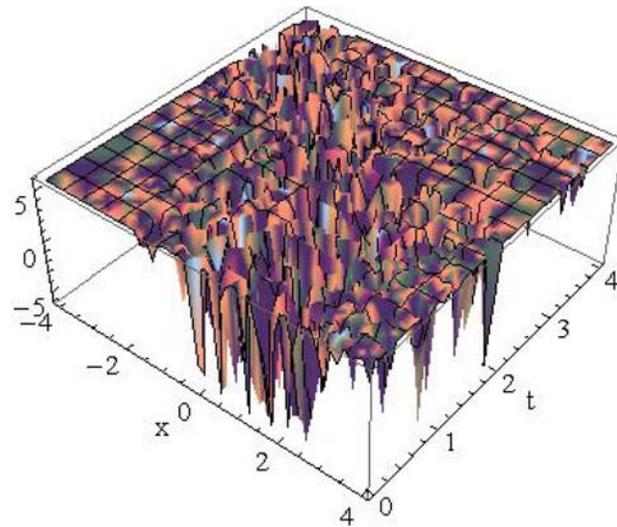


(b)

Figure 1. (a) shows the behaviour of the solution $U_1^*(x, t)$ without the effect of Lévy white noise. (b) shows the effect of Lévy white noise on the solution $U_1^*(x, t)$. Here, $\gamma_0 = L = -1$, $\gamma_1 = 2$, $\alpha = 0.5$ and $f(t) = \exp(t^2)/2$.



(a)



(b)

Figure 2. (a) shows the behaviour of the solution $U_2^*(x, t)$ without the effect of Lévy white noise. (b) shows the effect of Lévy white noise on the solution $U_2^*(x, t)$. Here, $\gamma_0 = L = -1$, $\gamma_1 = 2$, $\alpha = 0.5$ and $f(t) = \sin(t^2)/2$.

Remark. In fact, if we impose the condition that a Lévy process $\eta(t)$ is continuous, then it has the form

$$\eta(t) = at + \sigma B(t), \quad (3.32)$$

where a and σ are constants and $B(t)$ is the real Brownian motion, so we are basically back to the Gaussian case. Therefore, we have a new white noise functional solutions of the Gaussian white noise Wick-type stochastic KdV equation. These solutions can be give, by using Equations (3.24), (3.25), and (3.32), in the form

$$U(x, t) = \gamma_1 - 4\gamma_0 c_1 L^2 - 12\gamma_0 c_2 L^2 \Phi^2(\Theta(x, t)), \quad (3.33)$$

with

$$\Theta(x, t) = L \left(x - \gamma_1 \alpha \left(at + \sigma B(t) - \frac{t^2}{2} \right) - \gamma_1 \int_0^t f(\tau) d\tau \right), \quad (3.34)$$

where $\Phi(\cdot)$ runs through all Jacobi elliptic function solutions of Equation (3.5).

4. Conclusion

This paper is devoted to use Lévy white noise setting, in particular, Lévy Wick product, Hermite transform and Kondratiev spaces to present a new approach to study the non-linear stochastic partial differential equations driven by Lévy white noise. Then, by using this approach and the F -expansion method, many exact stochastic Jacobi elliptic function and soliton-like solutions for the Lévy Wick-type stochastic KdV equation are showed. Obviously, the planner which we have proposed in this paper can be also applied to other non-linear partial differential equations in mathematical physics such as KdV-Burgers, modified KdV-Burgers, Sawada-Kotera, Zhiber-Shabat, and Benjamin-Bona-Mahony equations. Moreover, since $\Psi^\diamond(\cdot) = \Psi(\cdot)$ for any non-random function $\Psi(\cdot)$,

Equations (3.24) and (3.25) give a new set of exact solutions of the variable coefficients KdV equation (1.2), where $\Phi(\cdot)$ runs through all Jacobi elliptic function solutions of Equation (3.5).

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